

$$a \xrightarrow{\hspace{2em}} g(a) \xrightarrow{\hspace{2em}} f(g(a))$$

$f \circ g$ dif. em a e

$$\boxed{D(f \circ g)(a) = Df(g(a)) Dg(a)}$$

$\begin{matrix} m \times n & & n \times p & & p \times n \end{matrix}$

↑ Derivada da composta.



$$1- D(f \circ g)(1,1)$$

3×2

\parallel

$$Df(g(1,1)) Dg(1,1)$$

$$= Df(1,0) Dg(1,1)$$

3×2

2×2

etc.

$$a = (1,1)$$

$$g(a) = g(1,1)$$

$$g(1,1) = (1,0)$$



$$\frac{d}{dx} \arctan(u(x))$$

$$= \frac{u'(x)}{1+u(x)^2}$$

————— \parallel —————

2- $\sigma \equiv$ "sigma"

$\gamma \equiv$ "gamma"

$$\sigma(t) = F(\gamma(t))$$

$$\begin{array}{ccccc}
 t & \longmapsto & \gamma(t) & \longmapsto & F(\gamma(t)) \\
 \mathbb{R} & \longrightarrow & \mathbb{R}^3 & \longrightarrow & \mathbb{R}^1 \\
 & & & \searrow & \nearrow \\
 & & \sigma = F \circ \gamma & &
 \end{array}$$

$$\sigma(t) = F(\gamma(t))$$

$$\begin{array}{ccccc}
 D\sigma(t) \equiv \sigma'(t) & = & DF(\gamma(t)) & D\gamma(t) \\
 1 \times 1 & & 1 \times 3 & & 3 \times 1
 \end{array}$$

$$\left[\quad \right] \left[\quad \right]$$

$$F: \mathbb{R}^n \rightarrow \mathbb{R}, \quad DF(a) \equiv \nabla F(a) \equiv \underline{\text{gradiente de } F \text{ em } a.}$$

matriz vetor

$$F(x, y, z) = x^2 + y^2 + z^2 + 1$$

$$DF(x, y, z) = \begin{bmatrix} 2x & 2y & 2z \end{bmatrix}$$

$$\begin{aligned} DF(\gamma(t)) &= DF(\cos t, t^2, \cos t) \\ &= \begin{bmatrix} 2\cos t & 2t^2 & 2\cos t \end{bmatrix}. \end{aligned}$$

$$D\gamma(t) = \begin{bmatrix} \cos t \\ 2t \\ -\sin t \end{bmatrix}$$

$$\begin{aligned} \sigma'(t) &= \begin{bmatrix} 2\cos t & 2t^2 & 2\cos t \end{bmatrix} \begin{bmatrix} \cos t \\ 2t \\ -\sin t \end{bmatrix} \\ &= 4t^3. \end{aligned}$$

Repe de caduc.

$$F(x, y, z)$$

$$(x, y, z) = \gamma(t)$$

$$= (x(t), y(t), z(t))$$

$$\sigma(t) = F(\gamma(t)) = F(x(t), y(t), z(t))$$

$$\sigma'(t) = \frac{\partial F}{\partial x} \frac{dx}{dt} + \frac{\partial F}{\partial y} \frac{dy}{dt} + \frac{\partial F}{\partial z} \frac{dz}{dt}$$

$$(x(t), y(t), z(t))$$

$$t \longrightarrow (x(t), y(t), z(t)) \longrightarrow F(\gamma(t))$$

$$t \mapsto \underbrace{(x(t), y(t), z(t))}_{\gamma(t)} \mapsto F(\gamma(t))$$

\parallel
 $F(x(t), y(t), z(t))$

$$\sigma'(t) = 2x(t) \frac{dx}{dt}(t) + 2y(t) \frac{dy}{dt}(t) + 2z(t) \frac{dz}{dt}(t)$$

$$x(t) = \text{cost} \rightarrow \frac{dx}{dt}(t) = -\text{sint}$$

$$y(t) = t^2 \rightarrow \frac{dy}{dt}(t) = 2t$$

$$z(t) = \text{csnt} \rightarrow \frac{dz}{dt}(t) = -\text{csnt}$$

$$\sigma'(t) = 4t^3$$

3- $f \circ g$

$$g: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$\mathbb{R}^2 \xrightarrow{g} \mathbb{R}^3 \xrightarrow{f} \mathbb{R}$$

$$(0,0) \mapsto \underset{\substack{\parallel \\ (0,1,2)}}{g(0,0)} \mapsto f(g(0,0)) = f(0,1,2)$$

$$D(f \circ g)(0,0) = Df(g(0,0)) Dg(0,0)$$

$$= Df(0,1,2) Dg(0,0)$$

$$= \begin{bmatrix} x & z \\ yz+z & l \\ 5 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 2 & 3 \\ 4 & 0 \end{bmatrix} = [2 \ 8]$$

$$D_{\mathcal{V}}(f \circ g)(0,0) = D(f \circ g)(0,0) \cdot \mathcal{V}$$

$$\mathcal{V} = (1, 2)$$

$$= \begin{bmatrix} 2 & 8 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 18$$



$$4- \sigma(x) = f(\sin x, x + e^x)$$

$$\begin{array}{ccc} \mathbb{R} & & \mathbb{R}^2 & & \mathbb{R}^3 \\ x & \xrightarrow{g} & (\sin x, x + e^x) & \xrightarrow{f} & f(g(x)) \\ & & \underbrace{\hspace{10em}}_{g'(x)} & & \end{array}$$

$$\sigma'(0) = Df(g(0)) Dg(0)$$

$$g(0) = (0, 1)$$

$$Dg(x) = \begin{bmatrix} \cos x \\ 1 + e^x \end{bmatrix} \quad g(x) = (e^x, x + e^x)$$

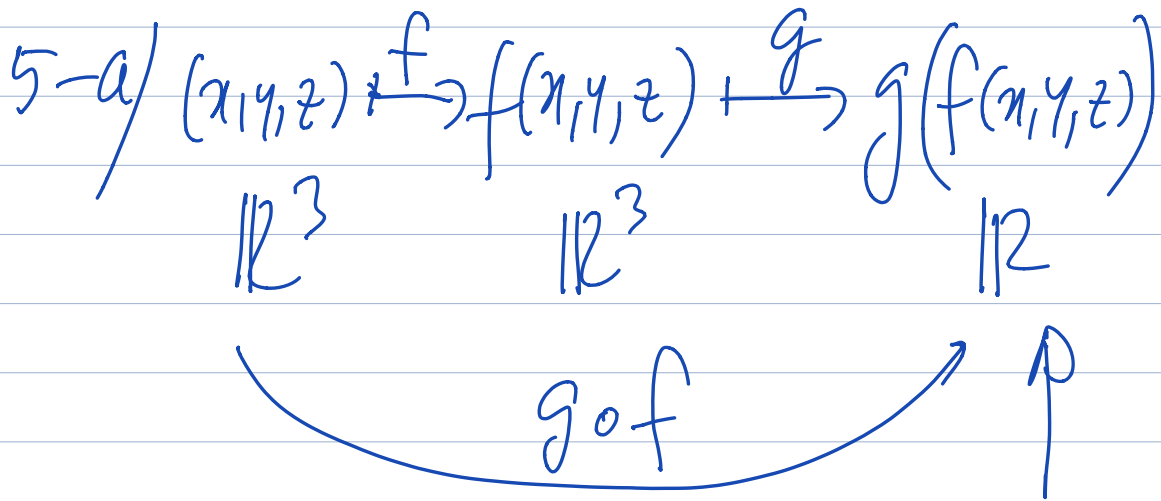
$$Dg(0) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\sigma'(0) = Df(g(0)) Dg(0)$$

$$= Df(0, 1) Dg(0)$$

$$= \begin{bmatrix} 1 & 0 \\ 2 & 1 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 4 \\ 7 \end{bmatrix}$$



$$D(g \circ f)(1, 1, 0) = Dg(f(1, 1, 0)) Df(1, 1, 0)$$

1×3 1×3 3×3

$$\begin{bmatrix} 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 3 \end{bmatrix} \begin{bmatrix} -2y^2 \\ 1 & 1 \\ -2z & 1 \end{bmatrix}$$

$-2 + 0 + 3 = 1$

$(1, 1, 0)$

$$f(1, 1, 0) = (2, 2, 1)$$

$$\nabla g(2, 2, 1)$$

$$Dg(2, 2, 1) = \begin{bmatrix} -1 & 0 & 3 \end{bmatrix} = (-1, 0, 3)$$

Usar type de cadeia
para $g: \mathbb{R}^3 \rightarrow \mathbb{R}$.

$$\underbrace{g(f(x, y, z))}_{h(x, y, z)} = g(u(x, y, z), v(x, y, z), w(x, y, z))$$

$$(x, y, z) \mapsto (u(x, y, z), v(x, y, z), w(x, y, z)) \xrightarrow{g(\cdot)}$$

$$\nabla g(2, 2, 1) = Dg(2, 2, 1)$$

$$= \left[\frac{\partial g}{\partial u} \quad \frac{\partial g}{\partial v} \quad \frac{\partial g}{\partial w} \right]_{(2, 2, 1)}$$

$$\begin{aligned} \frac{\partial h}{\partial y}(1,1,0) &= \frac{\partial g}{\partial u}(2,2,1) \frac{\partial u}{\partial y}(1,1,0) + \\ &+ \frac{\partial g}{\partial v}(2,2,1) \frac{\partial v}{\partial y}(1,1,0) + \\ &+ \frac{\partial g}{\partial w}(2,2,1) \frac{\partial w}{\partial y}(1,1,0) \end{aligned}$$

————— || —————
 5-b) é diferente de 5a)
 porque g é dada em vez
 de Dg .

$$Dg(u,v,w) = [2u \quad -2v \quad e^w]$$

$$h = g \circ f$$

$$\frac{\partial h}{\partial z} = \frac{\partial g}{\partial u} \frac{\partial u}{\partial z} + \frac{\partial g}{\partial v} \frac{\partial v}{\partial z} + \frac{\partial g}{\partial w} \frac{\partial w}{\partial z}$$

etc.

$$7- \quad F(x, y, \overbrace{g(x, y)}^z) = 0 \quad \circ$$

$$\Leftrightarrow z = g(x, y)$$

$$\frac{\partial F}{\partial z}(x, y, z) \neq 0$$

$$F(x, y, z(x, y)) = 0 \quad \leftarrow$$

$$z(x, y) = g(x, y)$$

$$\left(\frac{\partial g}{\partial x}, \frac{\partial g}{\partial y} \right)$$

R. codeic

$$\frac{\partial F}{\partial x}(x, y, z(x, y)) + \underbrace{\frac{\partial F}{\partial z}(x, y, z(x, y))}_{\neq 0} \frac{\partial z}{\partial x}(x, y)$$

$$\frac{\partial z}{\partial x}(x, y) = \frac{\partial g}{\partial x}(x, y) = - \frac{\frac{\partial F}{\partial x}(x, y, z(x, y))}{\frac{\partial F}{\partial z}(x, y, z(x, y))}$$

$$F \left(\underset{\parallel}{u(x,y)}, \underset{\parallel}{v(x,y)}, \underset{\parallel}{w(x,y)} \right)$$

$$\begin{matrix} x & y & g(x,y) \end{matrix}$$

————— || —————

6- Repe de codic .

$$g \left(\underbrace{g(x^2, xy, x+y)}_{u(x,y)} + e^x, \underbrace{xy}_{v(x,y)}, \underbrace{g(x,x,x)}_{w(x,y)} \right)$$

$$= g(u(x,y), v(x,y), w(x,y))$$

$$u(x,y) = g(a(x,y), b(x,y), c(x,y)) + e^x$$